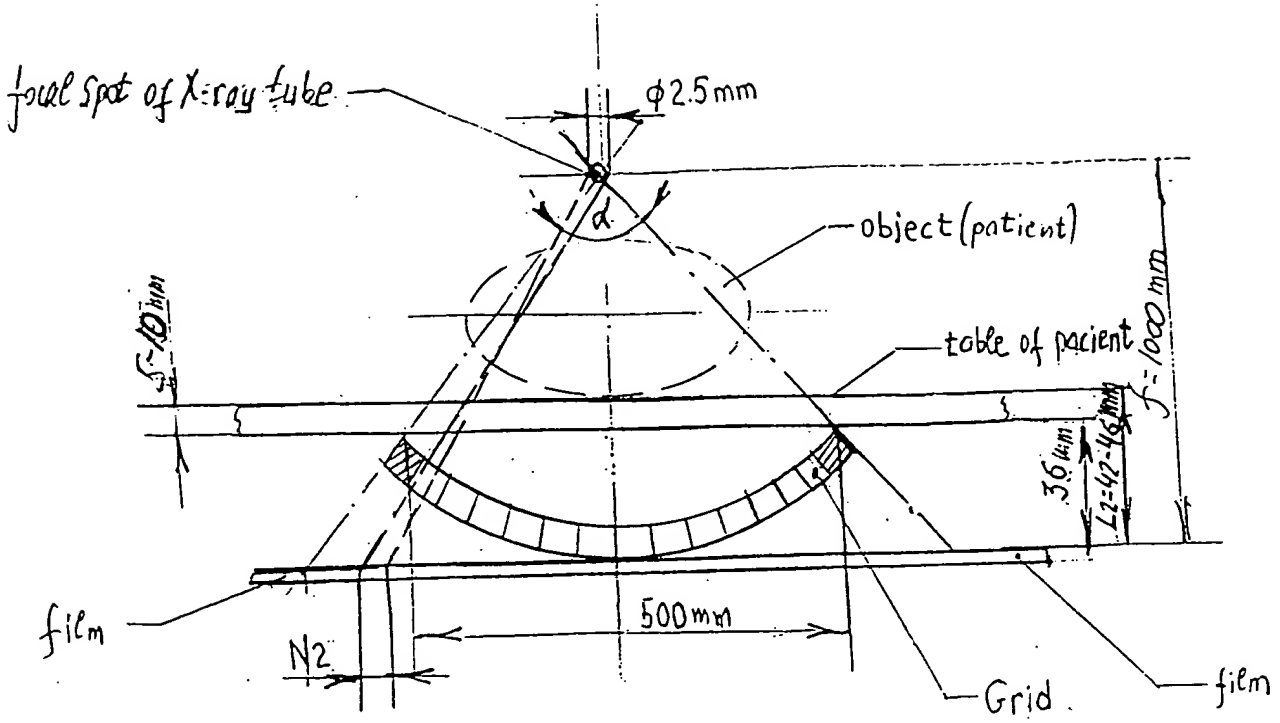


Fig. A

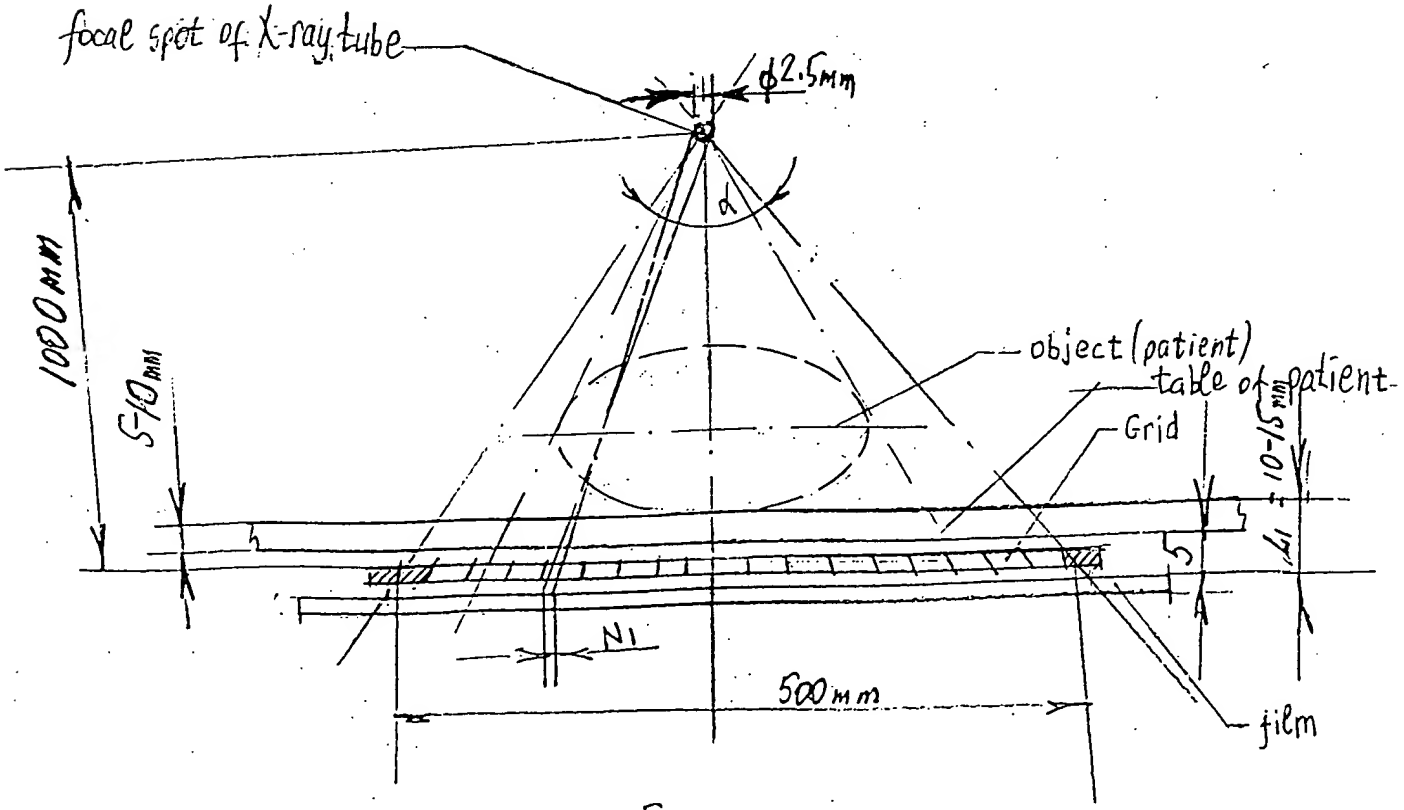
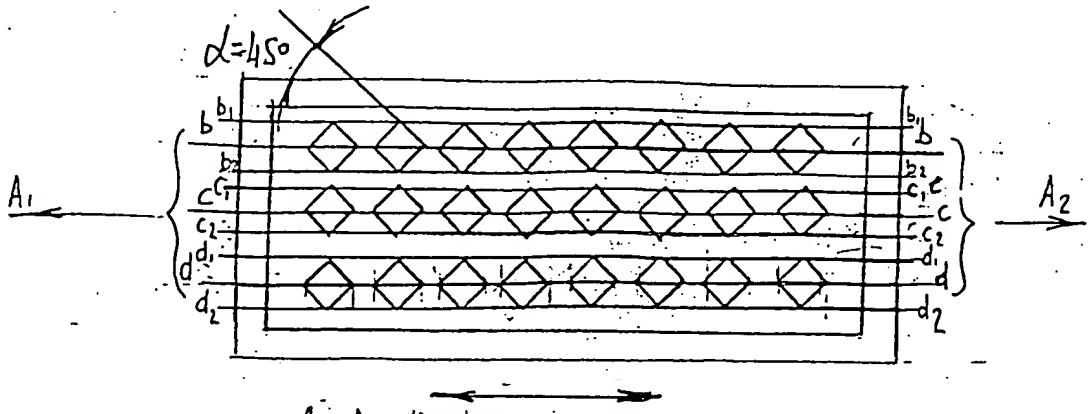
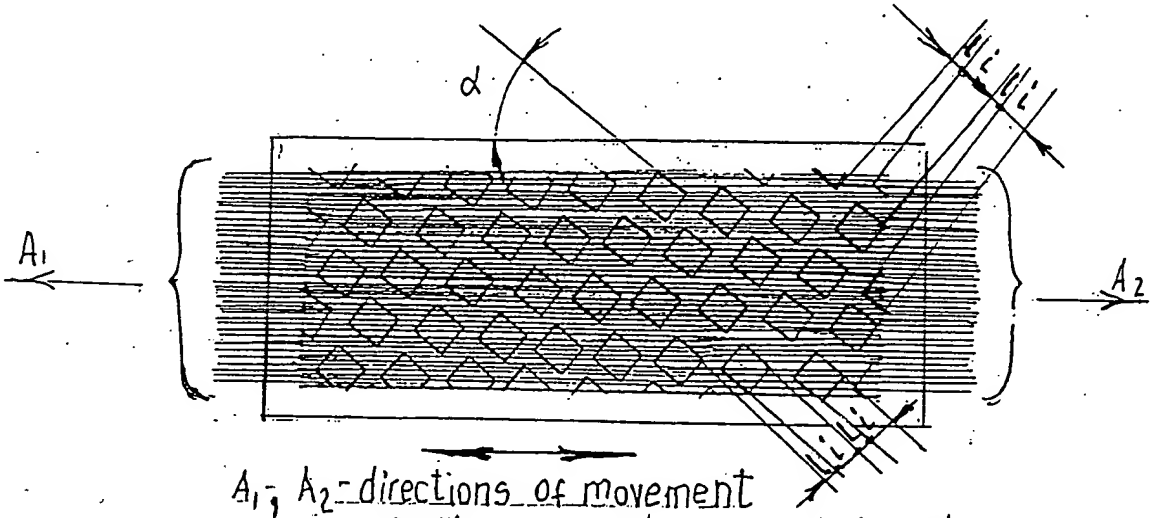


Fig B



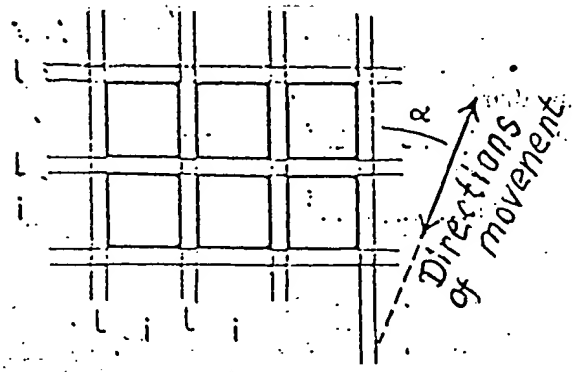
A_1, A_2 - directions of movement

Fig. C



A_1, A_2 - directions of movement

Design of grid by present invention



$$tg\,\alpha_1 = \frac{1}{3l+3i} \qquad tg\,\alpha_7 = \frac{l+i}{3l+2i} \;(= \cot\alpha_4)$$

$$tg\,\alpha_2 = \frac{1}{2l+2i} \qquad tg\,\alpha_8 = \frac{l+i}{2l+i} \;(= \cot\alpha_3)$$

$$tg\,\alpha_3 = \frac{1}{l+i} \qquad tg\,\alpha_9 = \frac{l+i}{l} \;(= \cot\alpha_2)$$

$$tg\,\alpha_4 = \frac{2l+i}{l+i} \qquad tg\,\alpha_{10} = \frac{2l+2i}{l} \;(= \cot\alpha_1)$$

$$tg\,\alpha_5 = \frac{3l+2i}{l+i} \qquad tg\,\alpha_{11} = \frac{3l+3i}{l} \;(= \cot\alpha_1)$$

$$tg\,\alpha_6 = \frac{2l+i}{2l+2i} \qquad tg\,\alpha_{12} = \frac{2l+2i}{2l+i} \;(= \cot\alpha_6)$$

Mattson's formulas

Fig. D

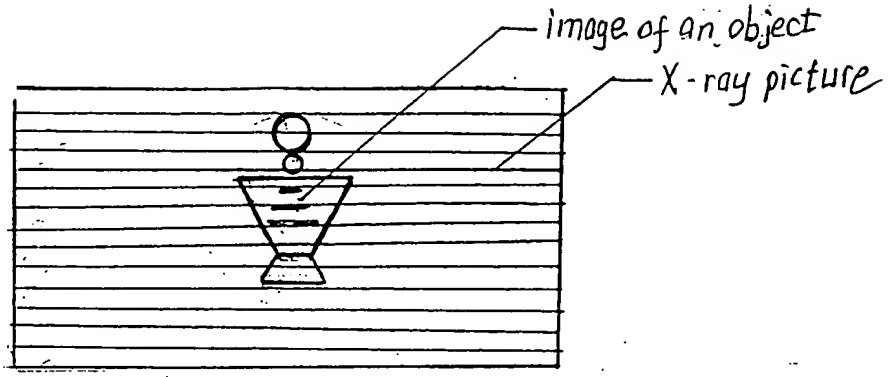


image of an object
X-ray picture

Fig. E

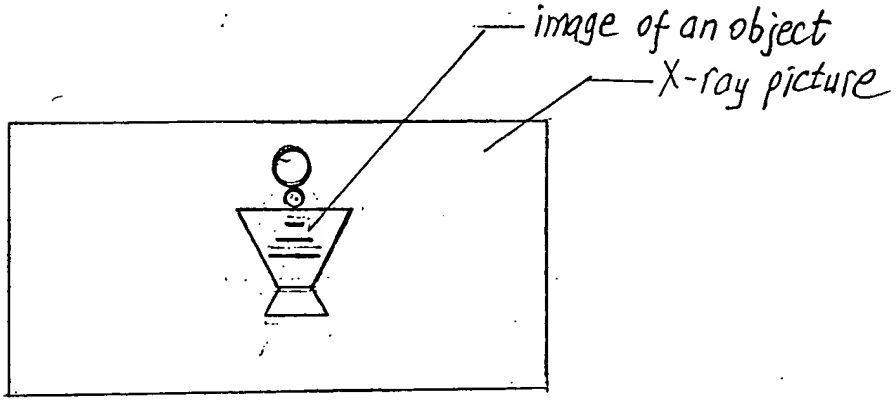


image of an object
X-ray picture

Fig. F